IOWA STATE UNIVERSITY

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# Smart Door Lock: Exploring Embedded Machine Learning for ISU Curriculum

### Motivation & Problem Statement

Iowa State University offers both embedded systems classes and machine learning classes but does not offer machine learning classes in the context of embedded applications. Therefore, students need a project or course, with real world applications, that teaches them machine learning through the lens of an embedded system. Our goal was to create such a project that could be integrated into the ISU curriculum.

### Solution

We have chosen a Smart Door Lock that recognizes a specific word and locks/unlocks a door, and we created corresponding lesson plans for implementing this project in a laboratory setting.

# Design Requirements



## **Functional Requirements:**

- Door (un)locks with  $\bullet$ correct keyword
  - User could still open door manually
- System takes in real time data from the user

# **Operating Environment:**

Classroom/Laboratory



Figure 1: Concept Sketch

### **Users & Uses**

Students:

- Laboratory component as part of ISU course
- Independent study
- Undergraduate research Professors & TAs:
- Laboratory component for their course
- Resource to provide to students to learn about embedded machine learning

### **Relevant Standards:**

- AI & Autonomous Systems
  - IEEE P7001
- (transparency) • IEEE P7002

- **ANSI** Grade 3
- **BHMA** Residential  $\bullet$ Security Grade C

**Non-Functional** 

### **Requirements:**

- Incorporate machine learning into an
- embedded system
- Appropriate technical complexity for ISU course
- Users must agree to have voice recorded
- (Un)locks door in 5 seconds
- Small enough to fit on door lock

**Engineering Constraints:** 

90% keyword accuracy

- Memory &
  - computational power of Arduino Nano 33
  - 256 KB SRAM

Gears disengage for unlocking with key Automatic actuation based on input from Arduino

1 MB Flash Ο

## Design Approach



Figure 3: Block Diagram

### Circuit

### **Requirements:**

- Switches control motors to (un)lock door
- Circuit is not externally powered

### **Details**:

- Arduino to program servo & DC motors
  - Wired on breadboard but have PCB file
- PWM used for DC motor

# Machine Learning Model

### **Requirements:**

- Take input as real time voice data from the Arduino mic
- Output as either Marvin, House, background noise, or unknown **Details:**
- Keywords: Marvin, House
- Edge Impulse used
- 20 distinct, real voices
- 10,157 total samples **Design Choices:**
- Using Edge Impulse
- 1D Convolution for ML model
- Real to synthetic data ratio
- Edge Impulse parameters

Input layer (650 features)
Reshape layer (13 columns)
1D conv / pool layer (8 neurons, 3 kernel size, 1 layer)
Dropout (rate 0.25)
1D conv / pool layer (16 neurons, 3 kernel size, 1 layer)
Dropout (rate 0.25)
1D conv / pool layer (32 neurons, 3 kernel size, 1 layer)
Dropout (rate 0.25)
Flatten layer
Add an extra layer
Output layer (4 classes)
Figure 4: ML Architecture

### Training:

- 4:6 real:synthetic data
- 80% of total data
- Learning rate of 0.0005
- 500 training cycles Testing:
- 20% of total data
- Done in Edge Impulse
- Confidence level of 0.6 **Results:**
- 1 ms latency
- 6.5K RAM usage
- 37.6K flash usage
- Final accuracy of 89.39%
- Limitations:
  - Not 100% accurate, which introduces security concerns in real world application

### **Design Choices:**

- Arduino Nano 33 BLE Sense
- Motors & switches

### Testing:

- Unit testing for servo & DC motor was done in parallel with circuit system testing
- Testing Environment: Arduino Serial Monitor and physical
- Results show both motors moving in the correct directions with triggering of the switches

Figure 7: Full Physical System



#### Figure 5: Circuit Diagram

- rigure 4. ML Architecture

### **Physical Model**

### **Requirements:**

- Must (un)lock door with switches
- 20 oz-in of torque on drive shaft **Details:**
- 2.16:1 gear ratio to increase torque
- 3D printed pieces

### **Design Choices:**

- Standard single cylinder lock
- Easily printed parts

### Testing:

- SolidWorks Assembly motion study
- Integration tests with each 3D printed piece
- System testing with final prototype
- Results: system constantly locks successfully, gears sometimes will skip when unlocking Limitations:
- 3D printing tolerances leave some play between parts causing backlash

# **DC** Motor imit switch Drive gear/shaf Limit switches Servo **9v** Battery Figure 6: Locking Mechanism



- ML Model not 100% accurate not secure enough for some real world scenarios
- Physically has same security as lock, which has standards that are consumer grade
- Implemented in a classroom setting for educational purposes, and therefore security implications have been noted but not fixed



# Lesson Plans

<sup>(</sup>data privacy)